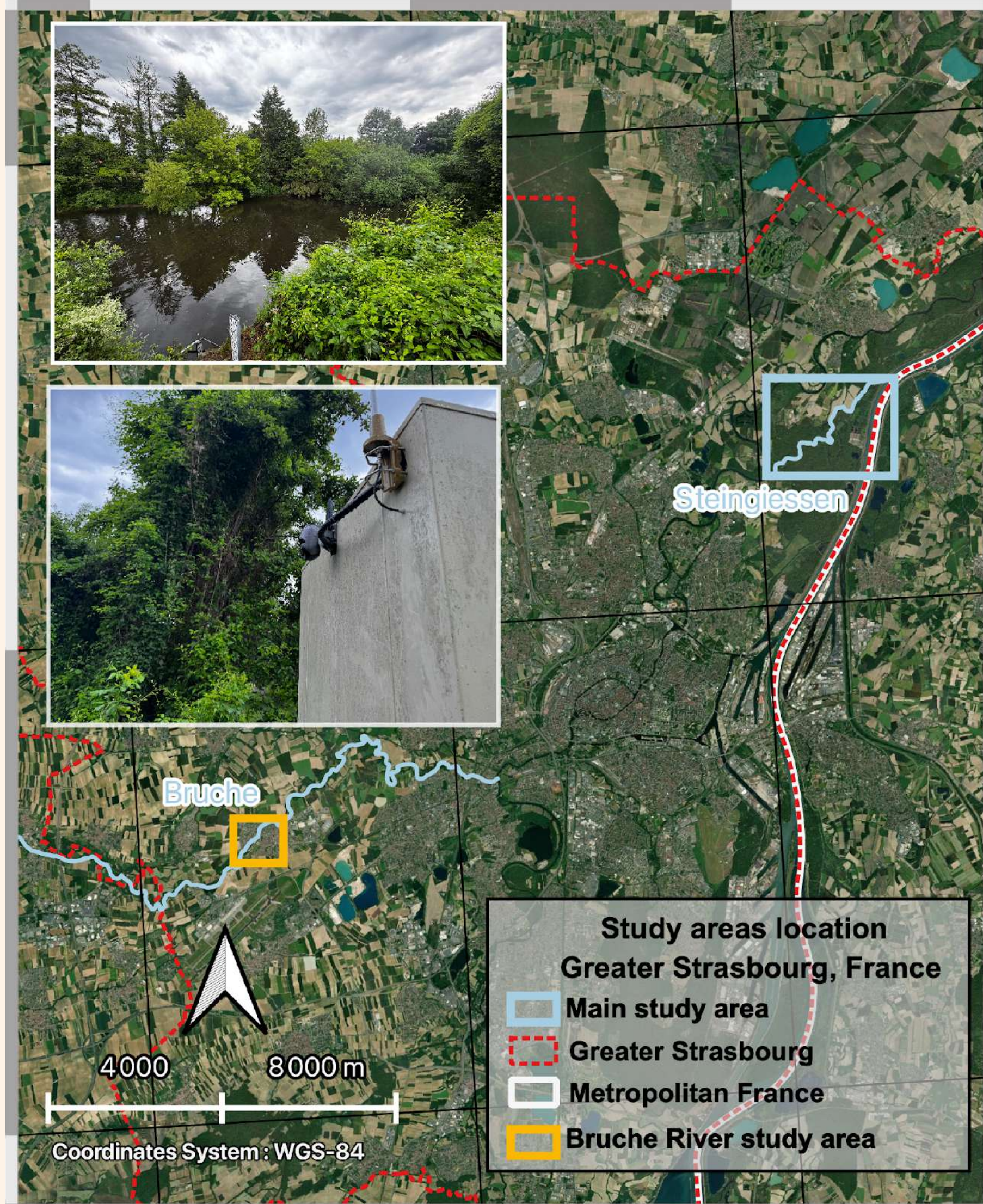


A Multimodal Data Fusion Framework for Riverine Macro-Debris Monitoring: Integrating Crowdsourced Data, Edge-AI, and Spatio-Temporal RFID Tracking

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Introduction



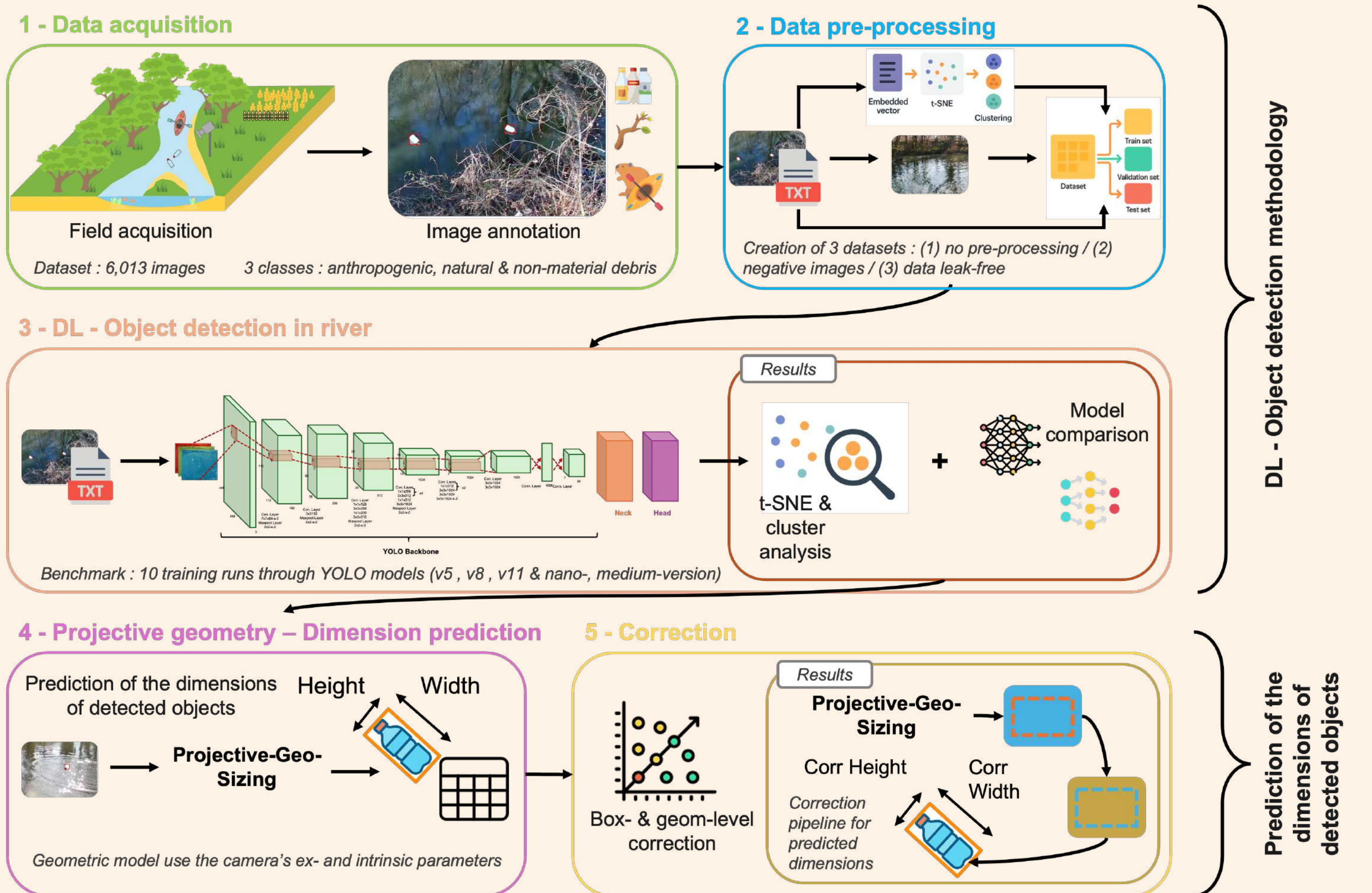
Issue : Rivers carry millions of tons of plastic to oceans, generating **microplastics**. They interact with logjams—altering **hydro-morphological dynamics**—and impact flora and fauna.

Challenge : current monitoring methods remain **sporadic, expensive, and difficult to replicate**.

Need : Developing **continuous, automated, and low-cost methods** to better understand plastic transport.

Methodology

I. Deep Learning-based debris detection



II. Spatio-Temporal RFID Tracking



Setup: RFID tags (433 MHz, 2.2s emission, 3-year battery) in **plastic bottles** to track their **spatio-temporal dynamics**.

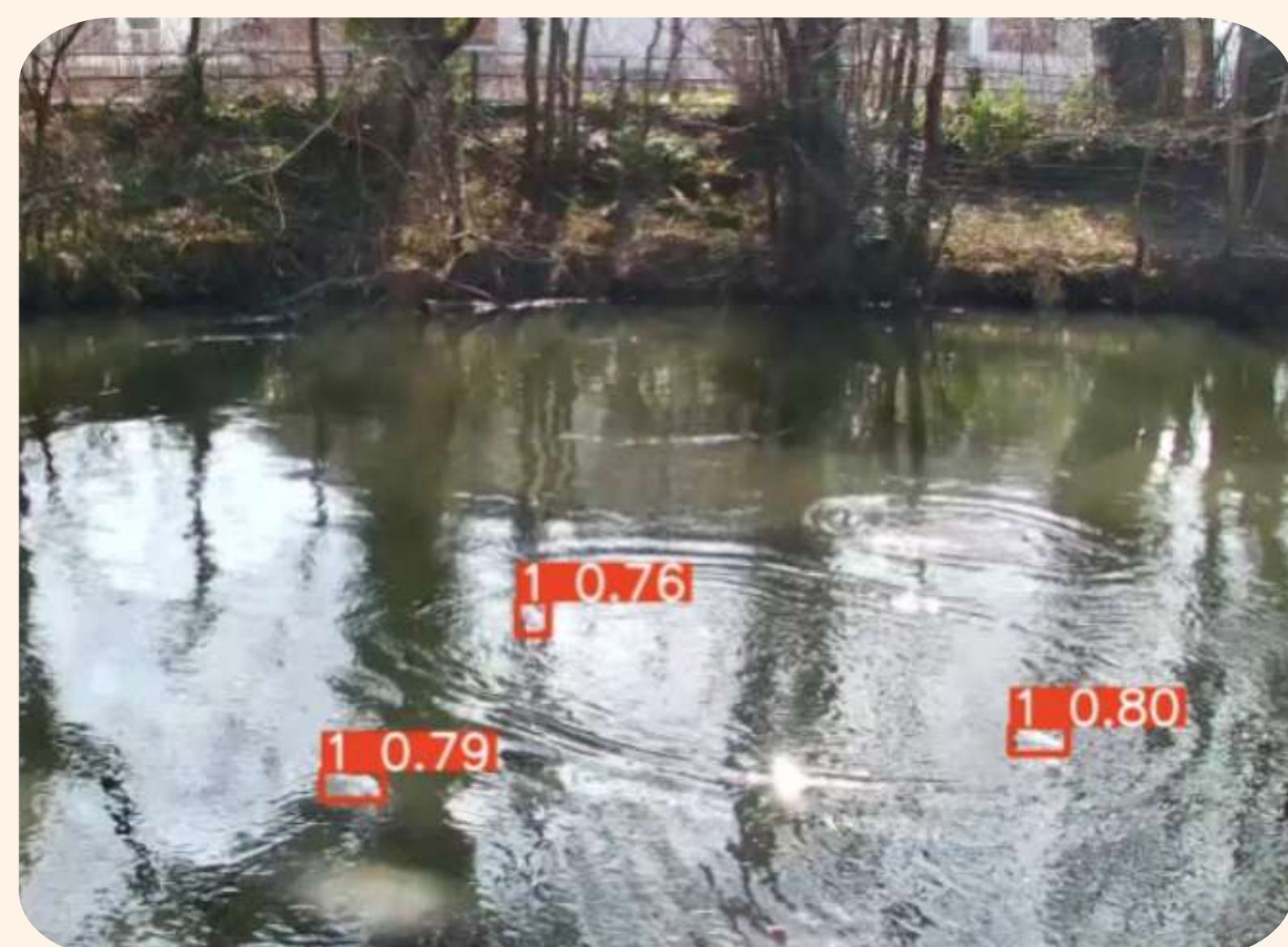
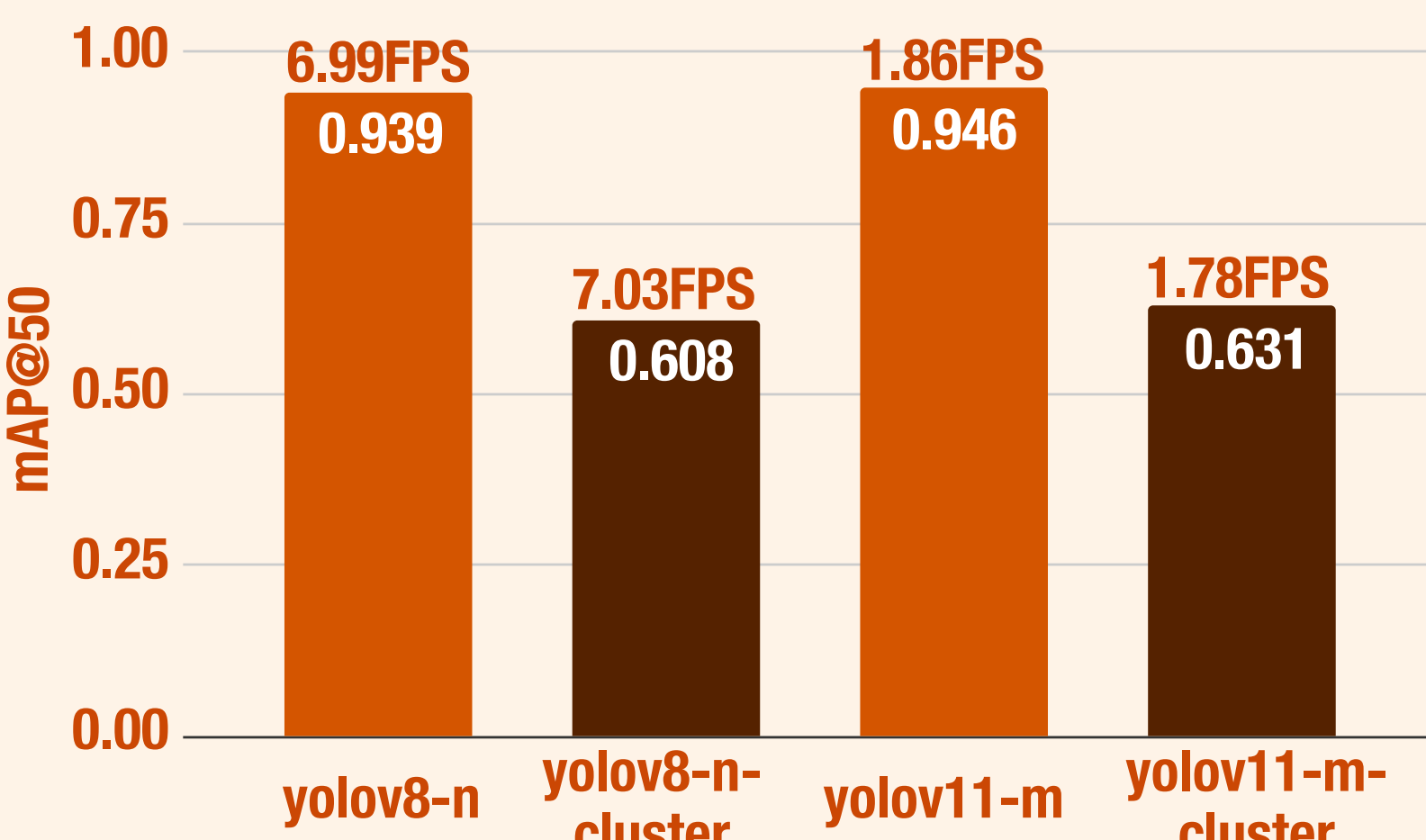
Deployment: Dropped in **Steingiesen River** on April 10th, 2025 (low flow velocity).

Monitoring: **Kayak** equipped with **RFID antenna** to map tag positions via signal strength.



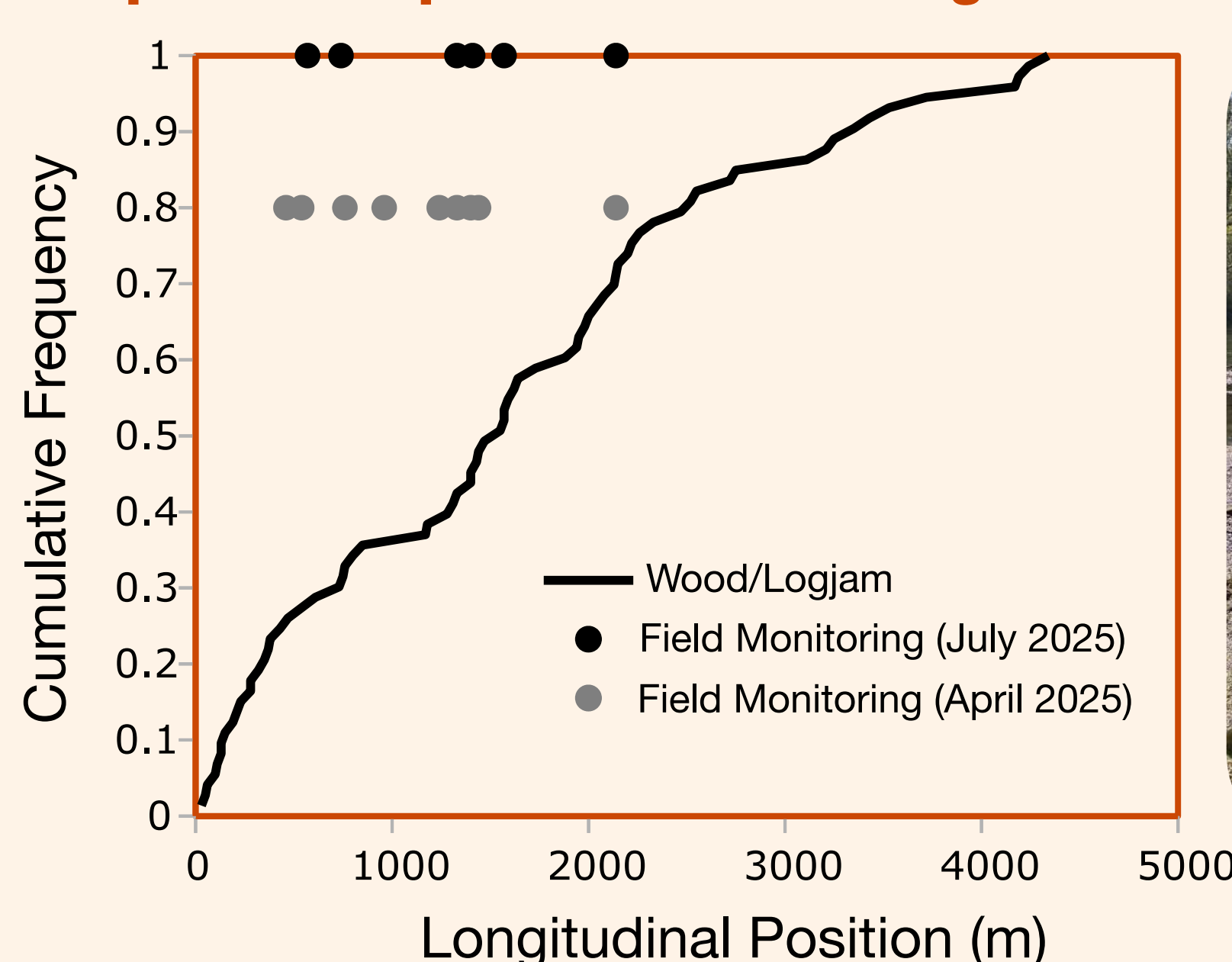
Results

I. Deep Learning-based debris detection



Robust detection under complex river conditions
YOLOv11-m achieves the **highest accuracy**
YOLOv8-n offers **best accuracy-efficiency trade-off** for embedded deployment.

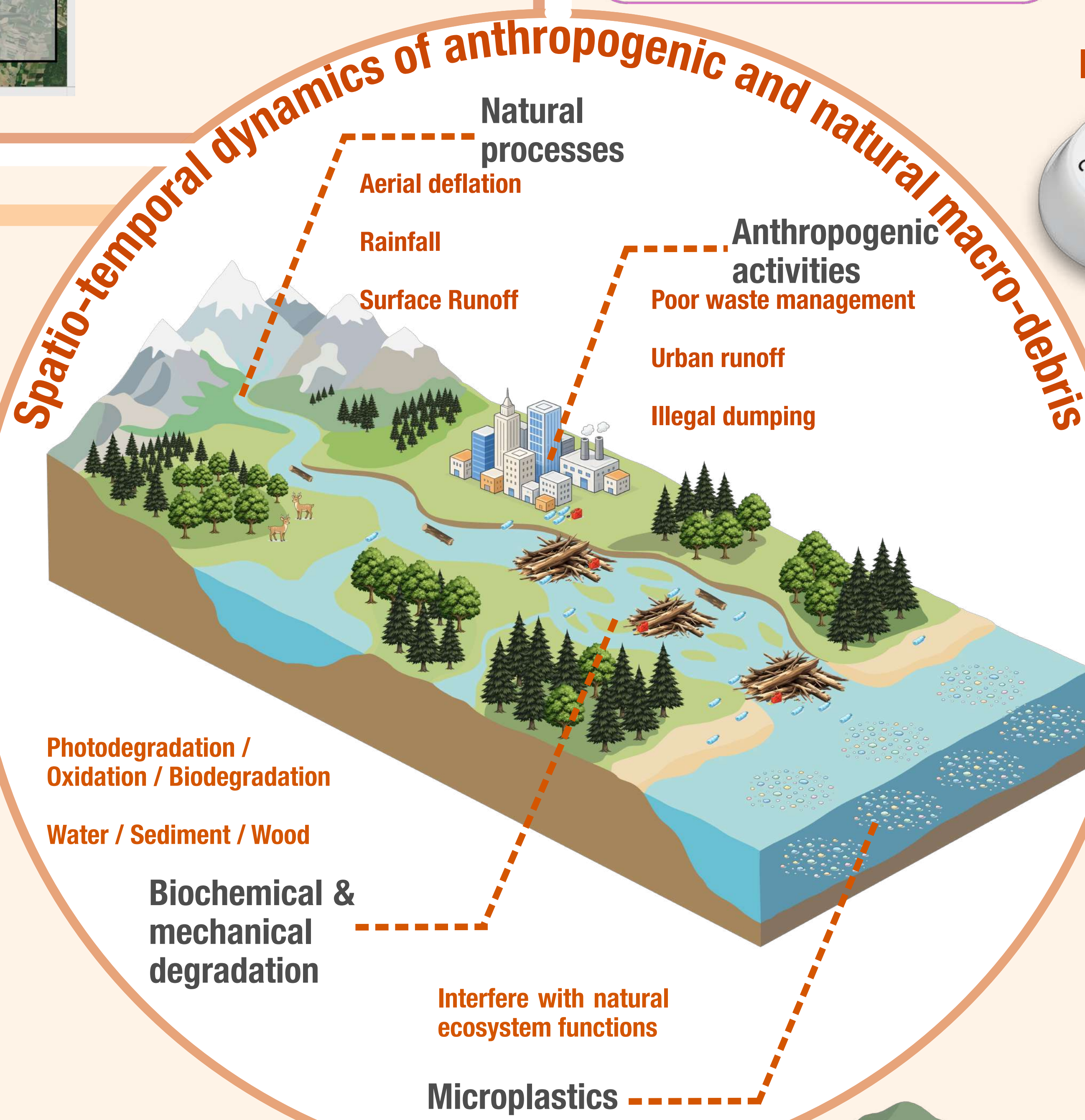
II. Spatio-Temporal RFID Tracking



Travel distance: between 380 and 2060 m (low flow velocity)

80% detection rate for RFID bottles

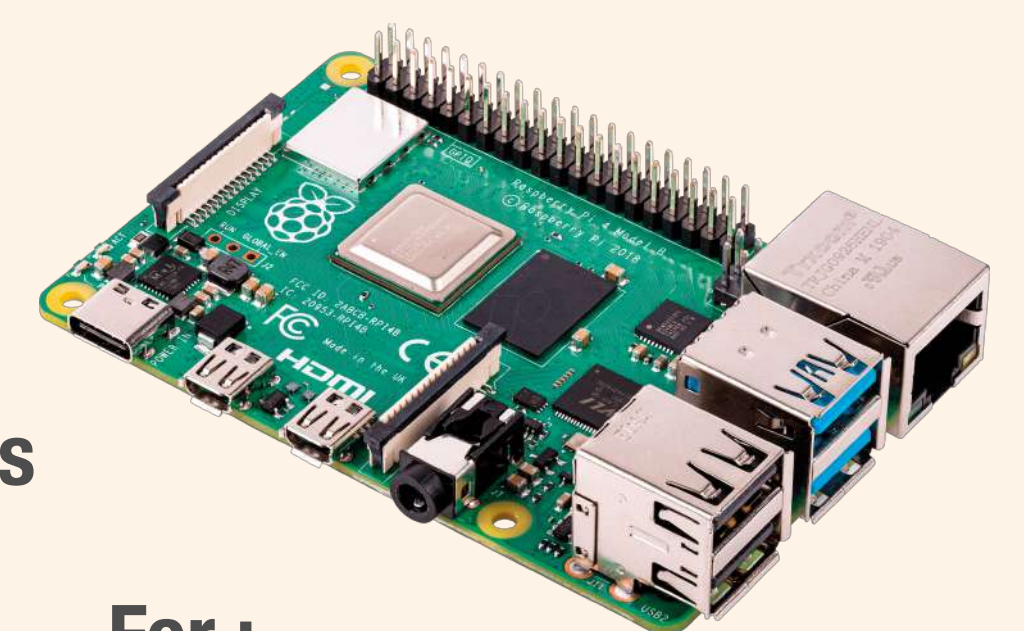
Trapping by natural logjams



Toward in-situ observatory

I. In-situ Edge-AI

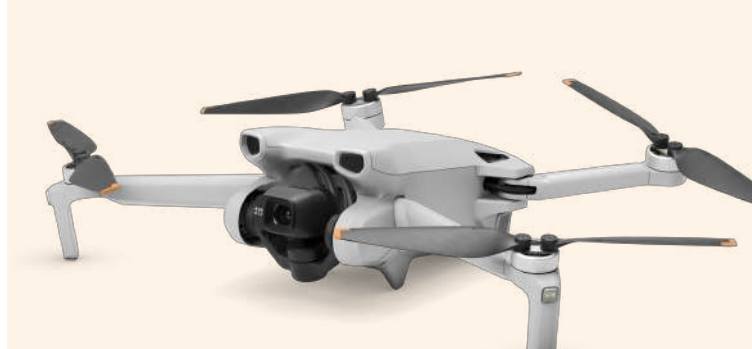
Camera station with :
- Raspberry Pi 5
- RGB & IR cameras
- Embedded AI models
- Low-cost sensors



For :
- Automated & continuous monitoring
- A scalable observatory
- Quantifying debris

III. Logjam characterization

Interactions between logjams and plastics



Using UAVs to build 3D models via SfM

Develop a **logjam typology** based on river channel and logjam morphological metrics

How to acquire more data ? :

- Fieldwork
- Webscraping
- Crowdsourcing **streampic.eu** :
- Based on citizen science
- Diverse sensors, viewpoints, debris type

